
Physics 1140 Fall 2013

Introduction to Experimental Physics

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Lecture 5:

Recap of Error Propagation and
Gaussian Statistics

Graphs and linear fitting

Experimental analysis

- Typically make repeat measurements of a quantity to estimate the uncertainty

1. Take many measurements of quantity.

2. Calculate the **sample average**. $\bar{x} = \frac{\sum_{i=1}^N x_i}{N}$

3. Calculate the **sample standard deviation**. $\sigma_x = \sqrt{\frac{\sum_{i=1}^N (x_i - \bar{x})^2}{N-1}}$

4. Calculate the **standard error on the mean**. $\sigma_{\bar{x}} = \frac{\sigma_x}{\sqrt{N}}$

5. Report measurement in **standard format**.

- One significant figure for uncertainty (or two, if first digit is a 1) and value rounded to same number of decimal places as uncertainty.

$$\boxed{\bar{x} \pm \sigma_{\bar{x}}} \text{ [units]}$$

Experimental analysis

- Derived quantity based on measured quantities, e.g. $T \approx 2\pi\sqrt{\frac{L}{g}}$
- Measure L and T and estimated associated uncertainty.
- Calculate uncertainty in derived quantity (e.g. g) using master equation of error propagation:

$$\sigma_f = \sqrt{\left(\frac{\partial f}{\partial x}\right)^2 \sigma_x^2 + \left(\frac{\partial f}{\partial y}\right)^2 \sigma_y^2 + \left(\frac{\partial f}{\partial z}\right)^2 \sigma_z^2 + \dots}$$

- Works for any function!
 - But all uncertainties must be independent/uncorrelated

Experimental analysis

- Discussion / Conclusion
 - Your own words!
 - what was measured
 - did it meet up to expectations – always compare with theory, accepted value, or a value measured in another way, and report the discrepancy and the significance of the discrepancy
 - what were the sources of error – random, systematic
 - how could experiment be improved.
- Look at the rubric posted on the course websites, and sample lab reports for more feedback about how to structure the lab report.

Clicker Question 1

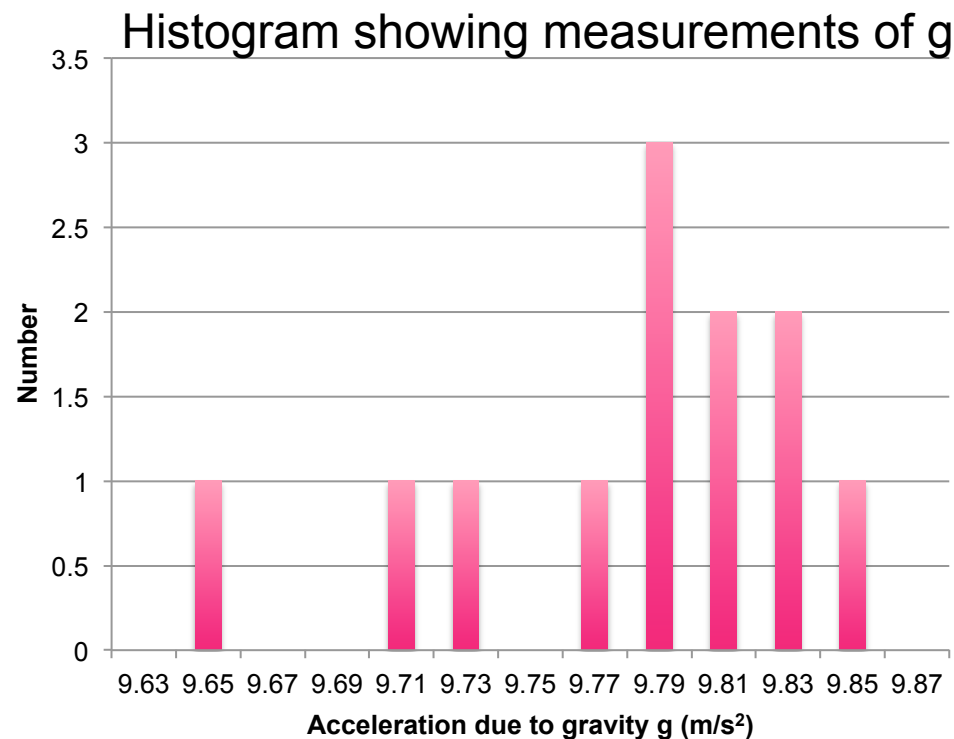
Which of the following will get “better” or decrease with an increase of the number of measurements?

A. The Standard Deviation

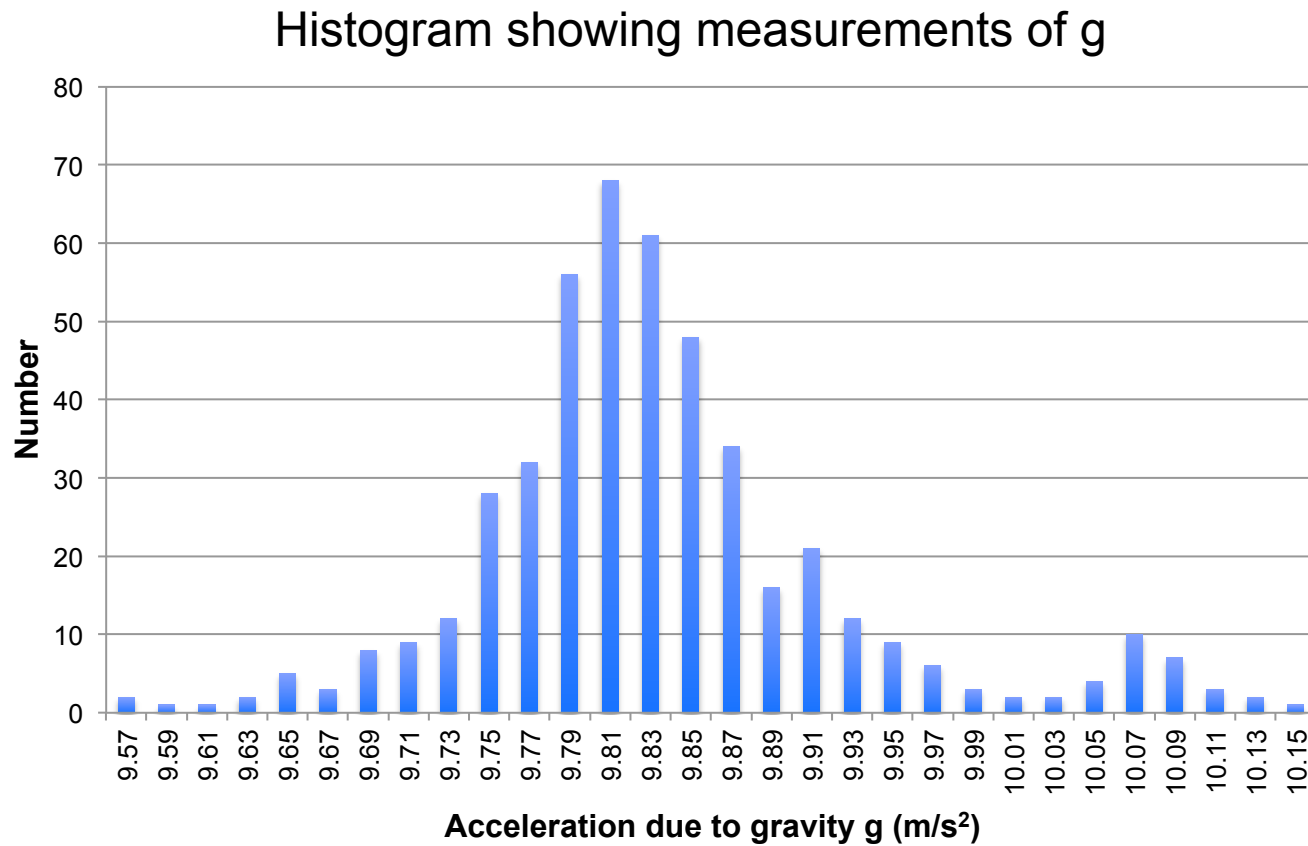
 B. The Standard Error on the Mean

Gaussian distribution

- If we make measurements of the same quantity using the same method
- If all measurements are uncorrelated/random
- The measurements distribute themselves according to the **Normal** or **Gaussian distribution**

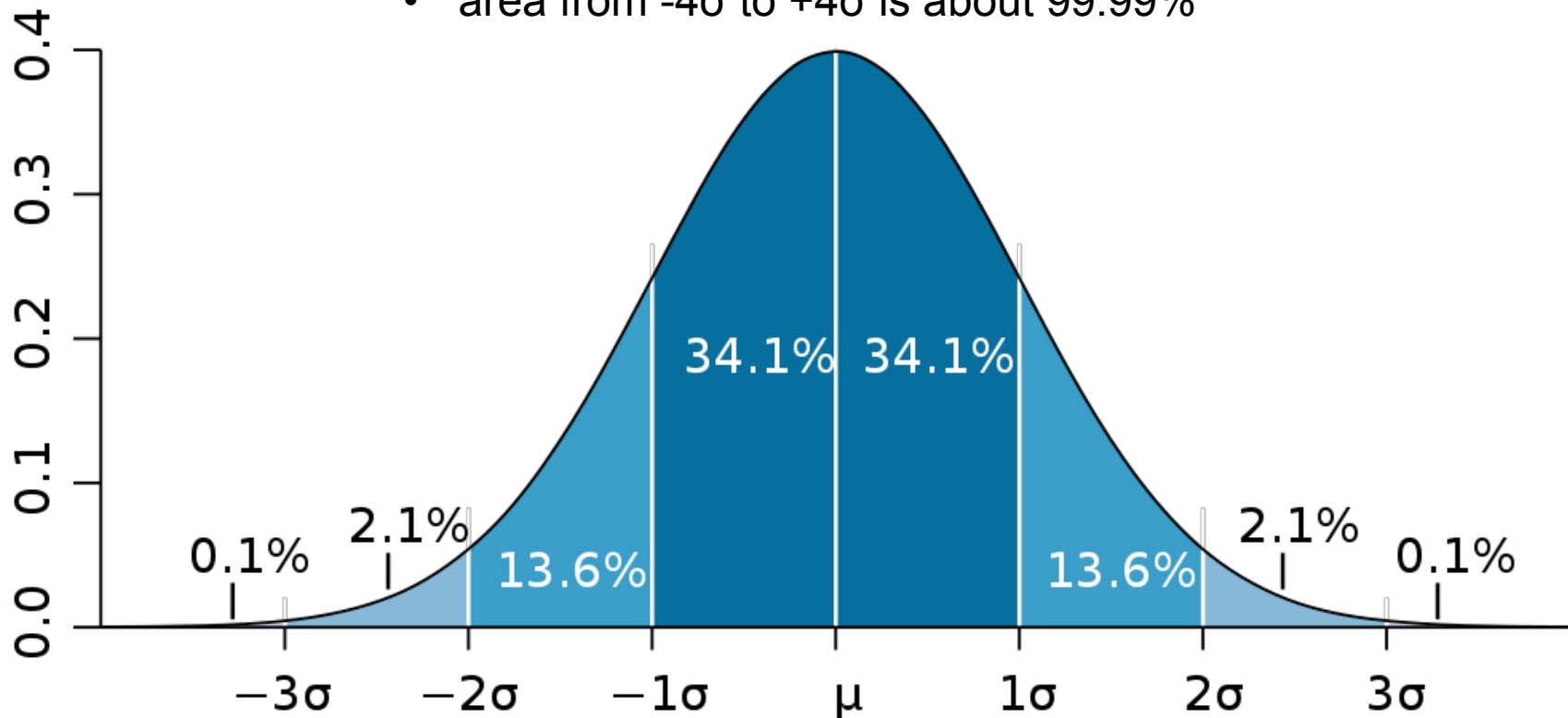


Large number of measurements



Significance and the Gaussian distribution

- area from $-\infty$ to $+\infty$ is 1
- area from $-\sigma$ to $+\sigma$ is about 68%
- area from -2σ to $+2\sigma$ is about 95%
- area from -3σ to $+3\sigma$ is about 99.7%
- area from -4σ to $+4\sigma$ is about 99.99%

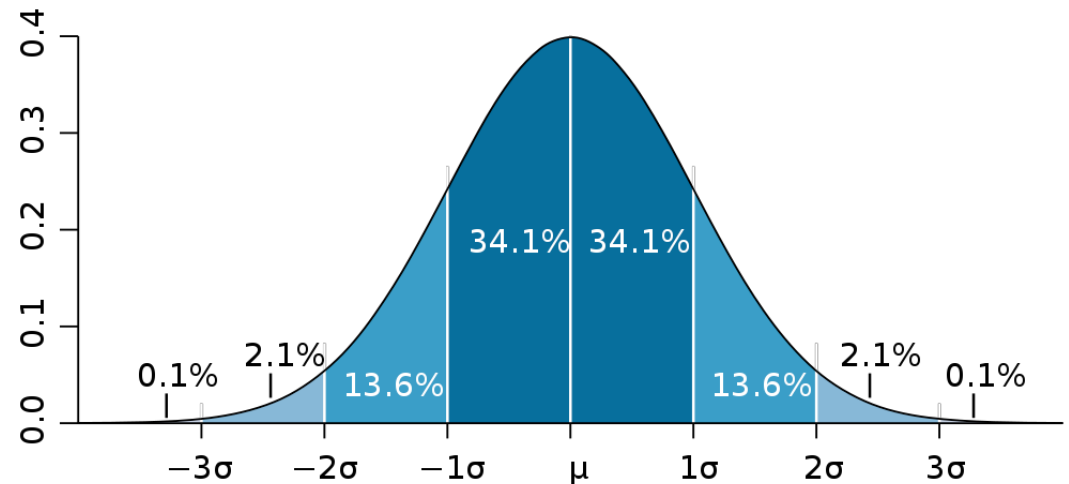


- Keep these values in mind as you write the conclusions of your reports.
- A discrepancy is significant if the probability to deviate that much by chance is small.

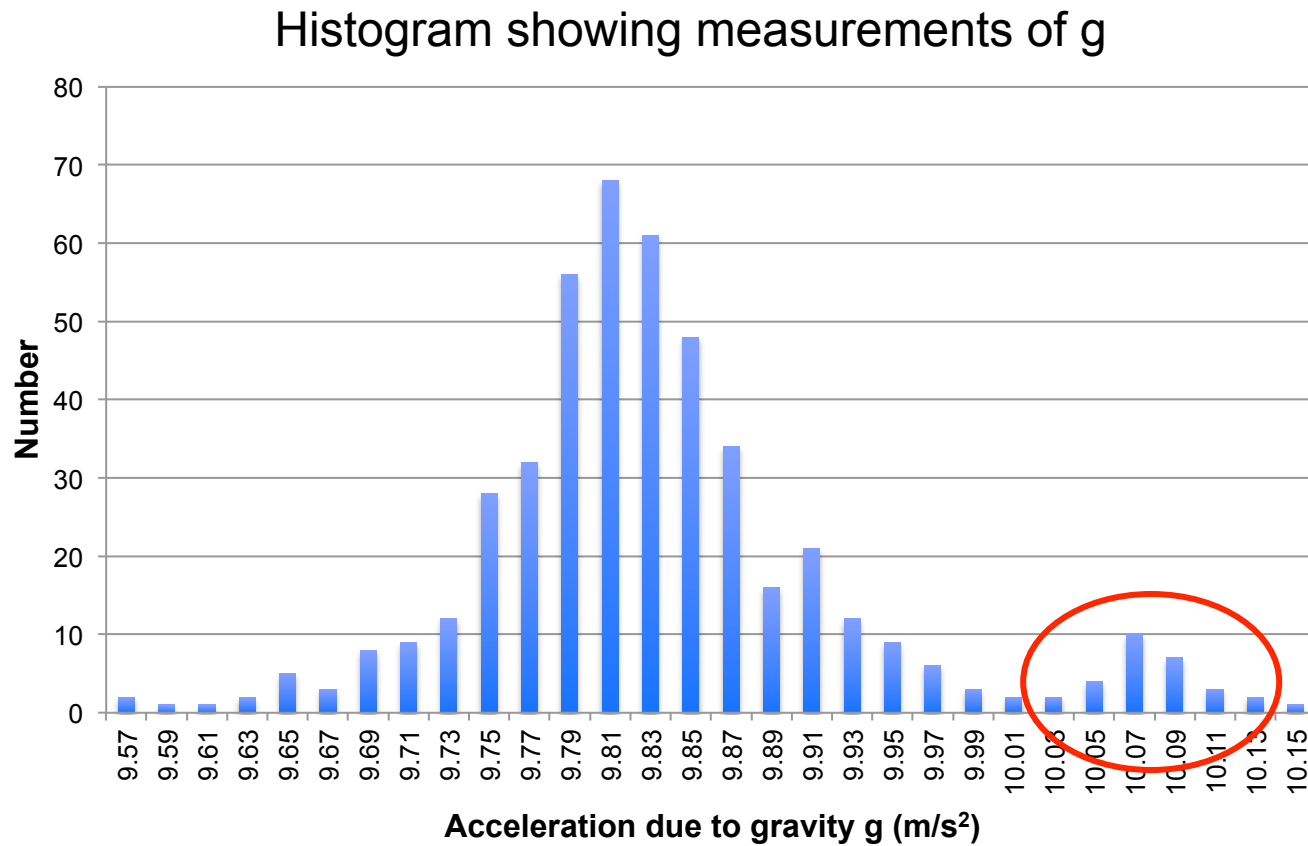
Clicker question 2

In a distant foreign country, the distribution of heights of adult males is found to be Gaussian with a mean of 5'10" and a standard deviation 3". What fraction of males are taller than 6'4"?

- A) less than 1%
- B) about 5%
- C) about 16%
- D) about 2.5%
- E) about 20%



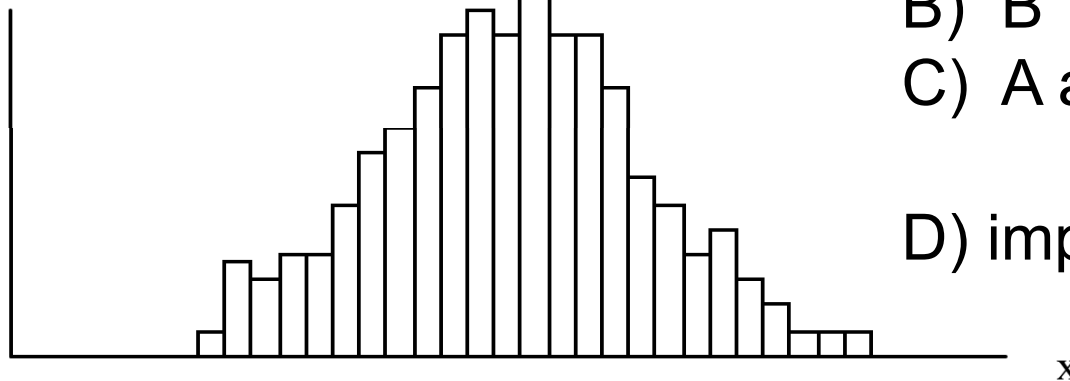
Random and systematic uncertainty



Clicker question 3

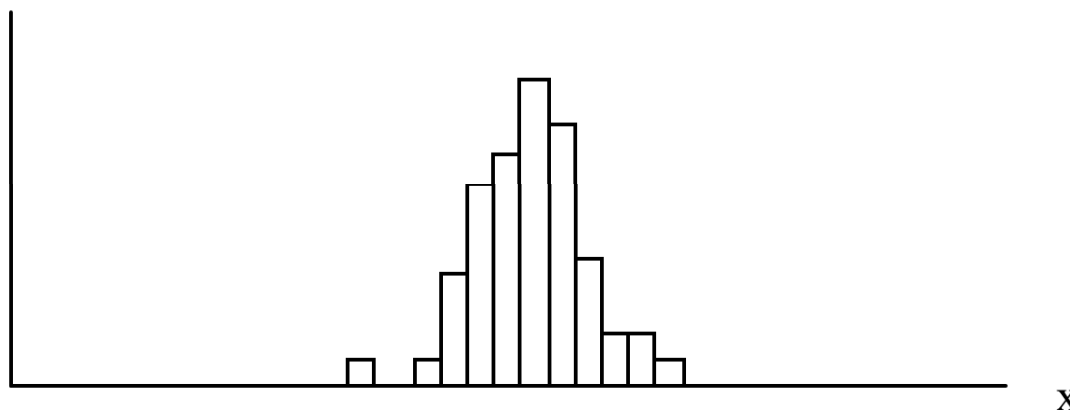
Which series of measurements has the smaller standard deviation σ ?

frequency Apparatus A



- A) A
- B) B
- C) A and B have the same standard deviation.
- D) impossible to tell from the information given.

frequency Apparatus B



Graphical methods

Often you will take a series of measurements where the input parameters are varied.

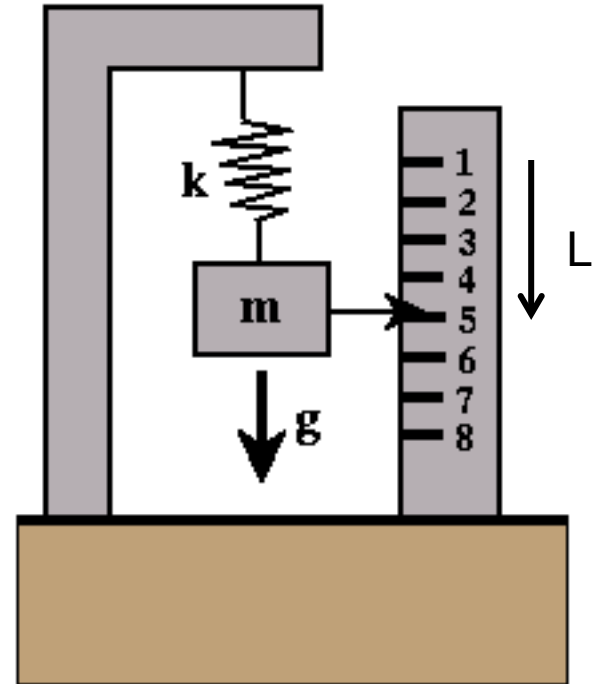
- Example: measure a spring constant:

$$F = mg = kL$$

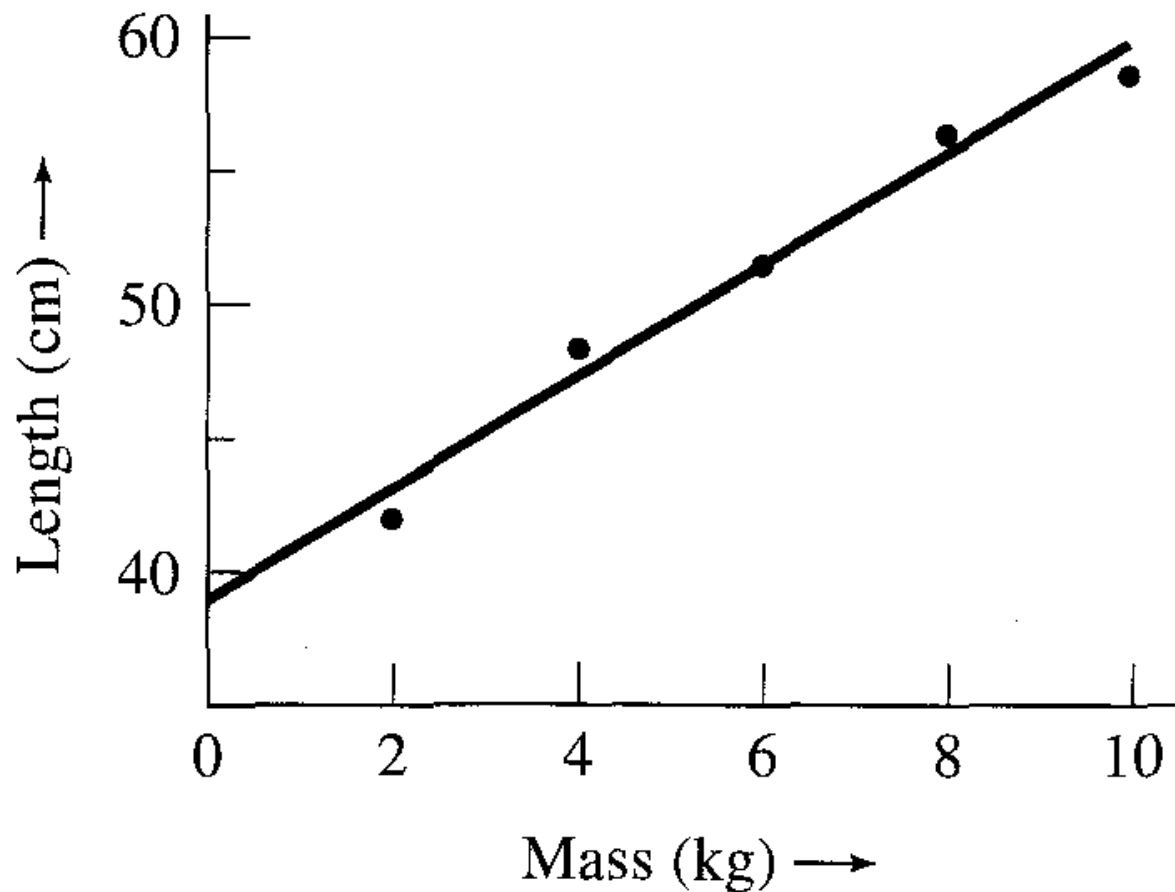
- measure many values of m and x

$$L = \frac{g}{k}m \text{ or } L = A + B \cdot m$$

- Where $B = g/k$ and A is the constant “zero” displacement



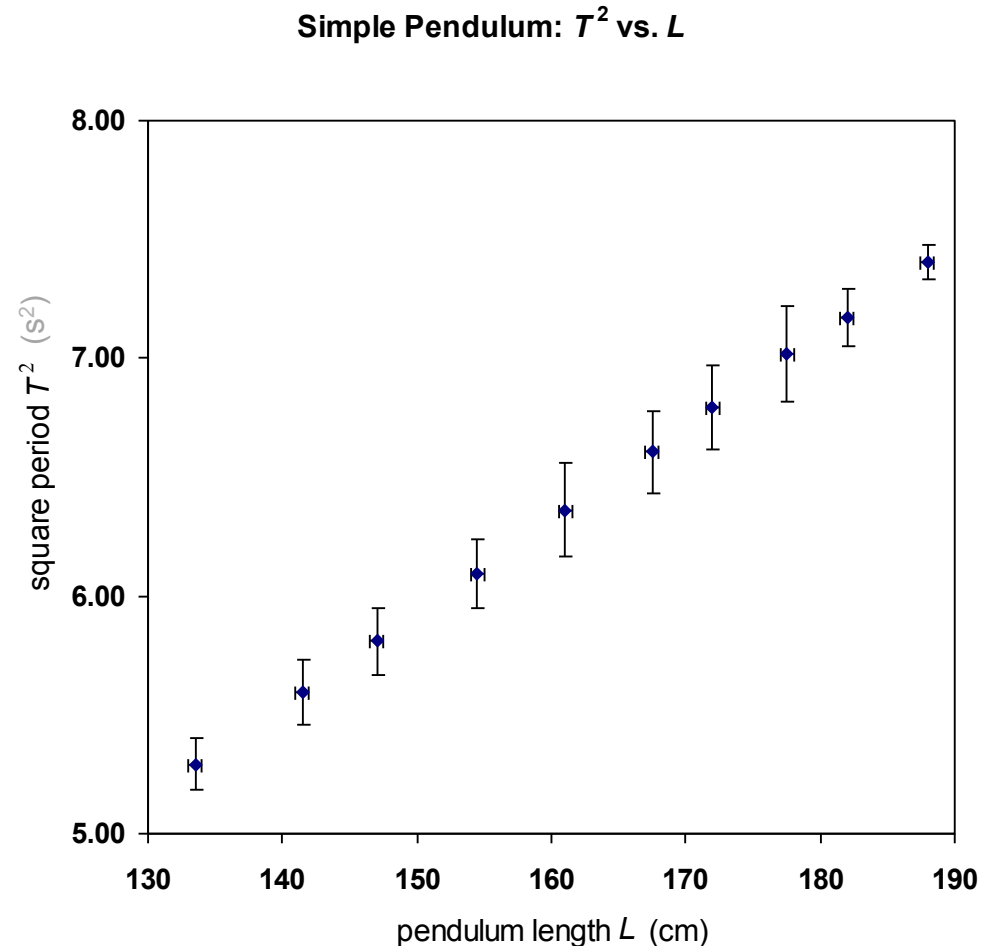
Linear relationship



Legend, axis labels, units, captions...

Graphical methods

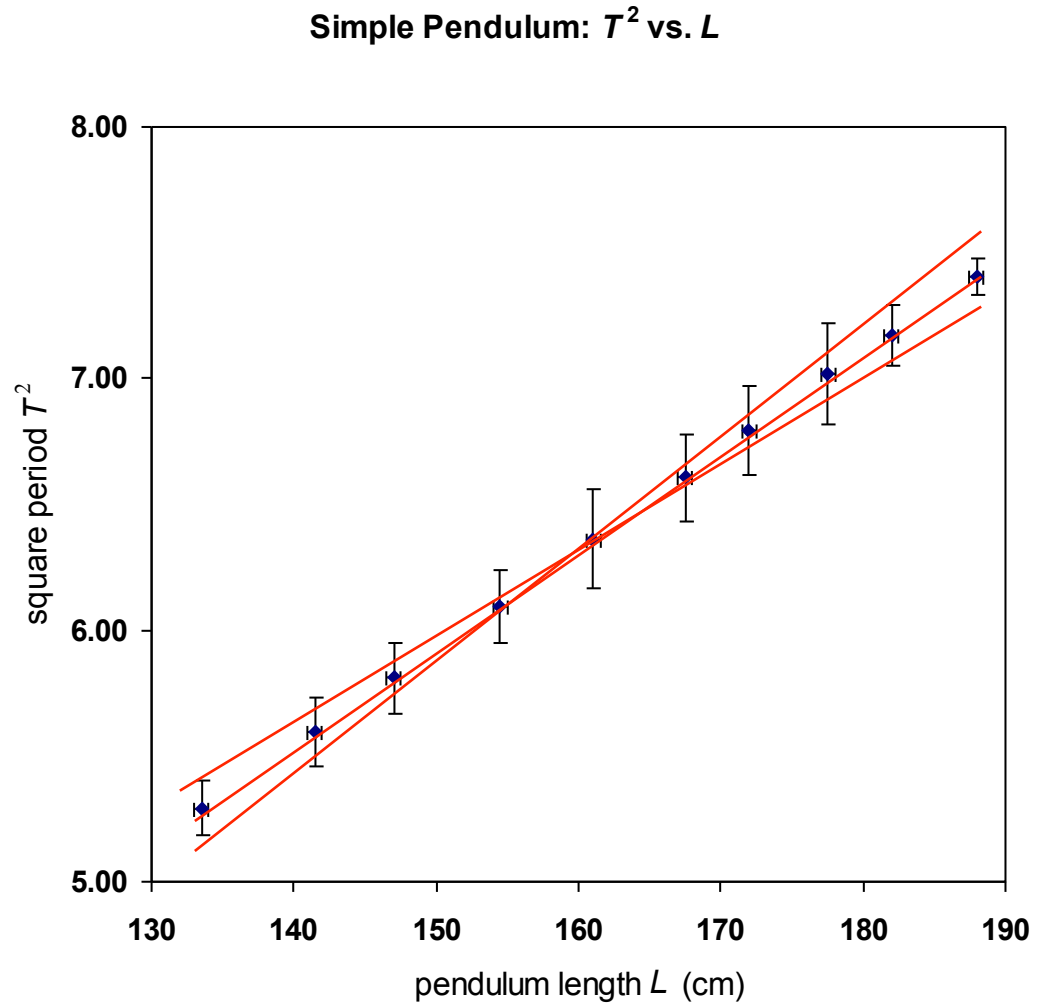
- When plotting data, you want to somehow show that there are uncertainties on your data points.
- Convention: show the 1σ errors on each data point using “error bars.”



Fitting

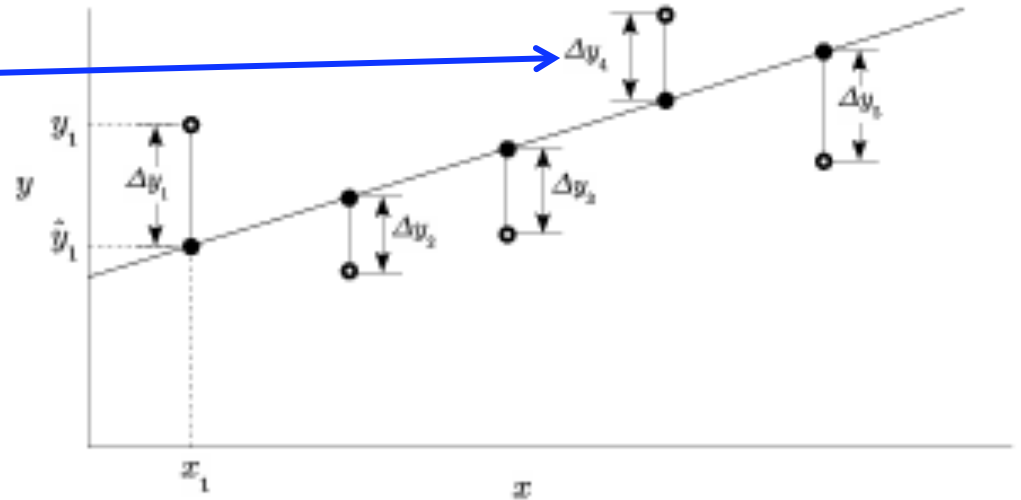
$$y = A + B \cdot x$$

- Fitting: find A and B that create the “best” line through the data.
- But, how do we define a line as the “best” fit?



Best fit line: least squares minimization

This difference, summed in quadrature for each point



- **Least squares method:** minimize the sum of the distance between each point and the line of best fit.
- The distances Δy are called the **residuals of the fit**.

$$\Delta y_i = y_i - \hat{y}_i, \text{ where}$$
$$\hat{y}_i = A + Bx_i$$

Least squares fitting

$y = A + B \cdot x$ - want to find A and B that best predict y for a given x .

$$\text{total error} = \sqrt{\sum_i (y_i - (A + Bx_i))^2}$$

- Want to minimize total error

– set derivative = 0! $\frac{\partial}{\partial A} \left(\sum_i (y_i - (A + Bx_i))^2 \right) = 0$

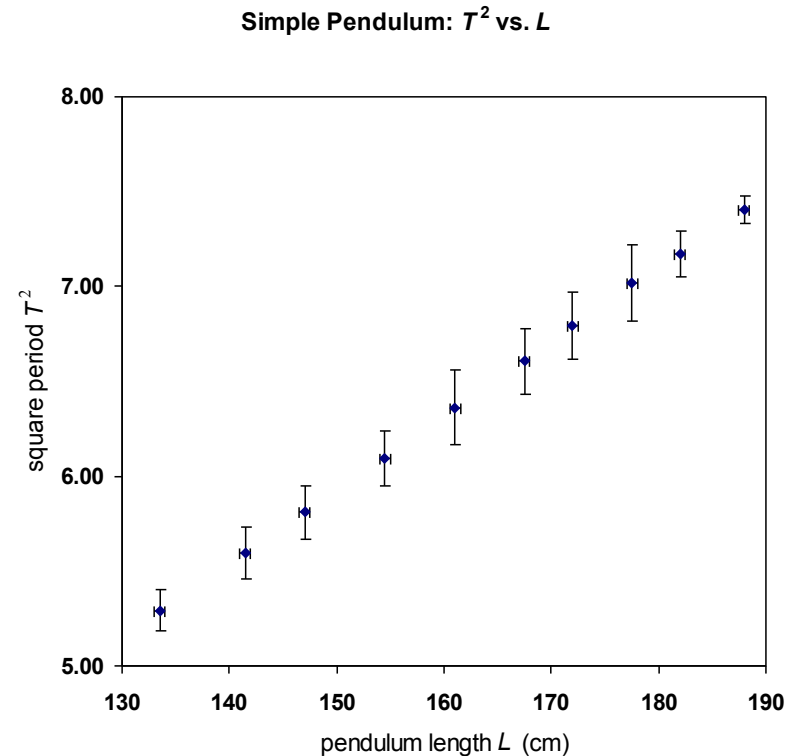
$$\frac{\partial}{\partial B} \left(\sum_i (y_i - (A + Bx_i))^2 \right) = 0$$

Result: get an estimate for A , B , σ_A , σ_B .

The formulae for A , B and their uncertainties are rather complicated, but very regular and easy for computers

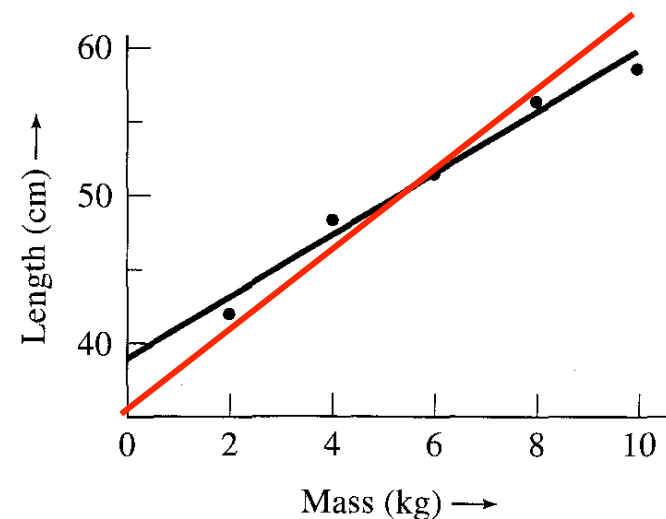
Fitting

- Mathematica code for doing linear fits provided:
Linfit.nb
 - calculates A , B , σ_A , σ_B .
- Can have extensions to least squares fitting to take into account points with different errors: weighted least squares fit.



Rules for linear fitting

- Sometimes, you expect from physical arguments that a linear fit should have **intercept = 0** (e.g. $x = v_0 t$, $F = ma$)
- Some programs allow you to force the intercept $A = 0$ when performing a linear fit.
- Suggested procedure:
 - Start by fitting your data to $y = A + Bx$. **Do not force $A = 0$!**
 - Using σ_A , see if the difference between A and zero (the expected value) is **statistically significant**
 - If not, you can try to perform the fit again forcing $A = 0$.
 - If so, keep the intercept. You may have found evidence for a **systematic error** in the location of your zero.

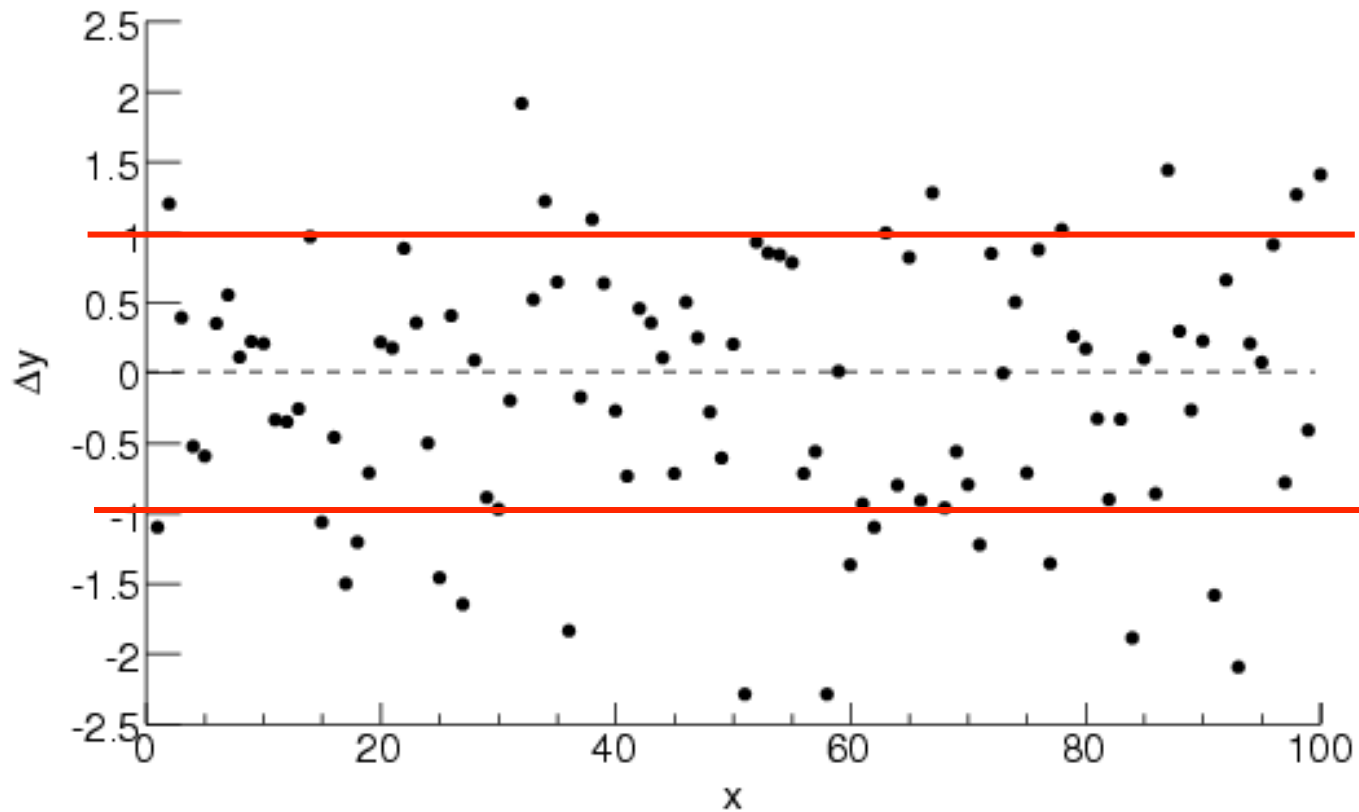


Goodness of fit

- You can perform a fit on any data set, but the function you choose **may or may not** be appropriate.
- One way to tell if your fit is good is to **plot the residuals** Δy as a function of x .
- You should expect that 68% of the residuals ($\sim 2/3$) should fall within 1σ of zero.
 - If less than 68% of the residuals are within 1σ of zero, you have probably **underestimated the random errors** in your data, or there is a systematic error.
 - If more than 68% of the residuals are within 1σ of zero, the fit is “too good.” You have probably **overestimated your errors**.
 - Remember, this is not exact. But *about* $2/3$ should fall within the error bars.

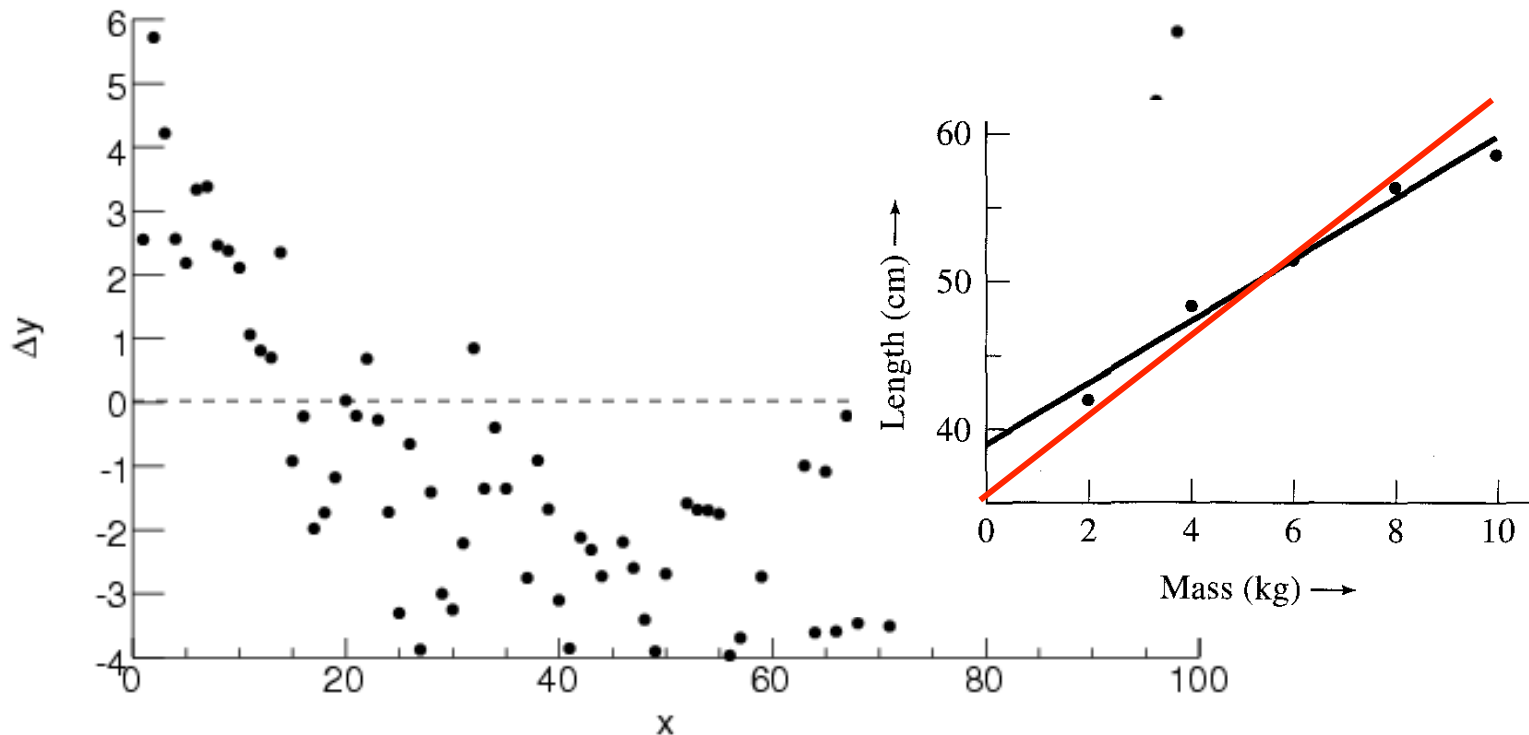
Appropriate residuals

- The ideal distribution of residuals has no observable pattern.



Incorrect fit or bias in the data

- If the wrong equation is fitted to the data, or there is some bias, your residuals may look like this:



Nonlinear data

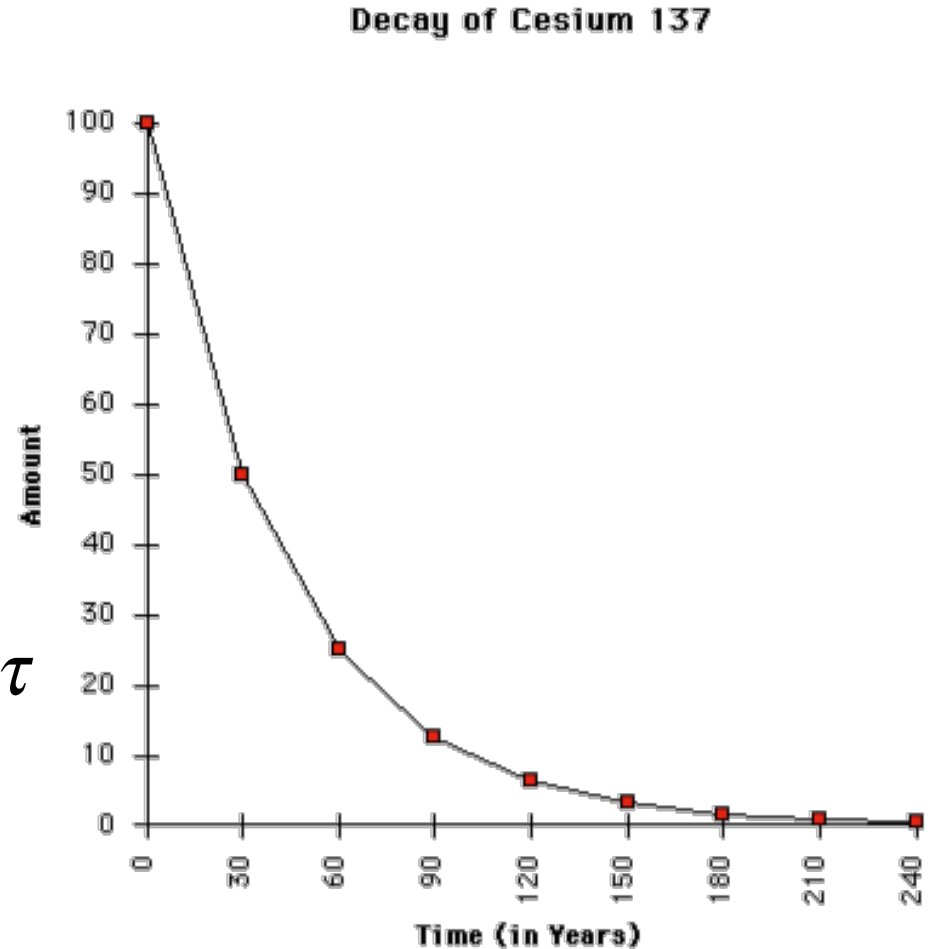
Example: exponential decay

$$N(t) = N_0 e^{-t/\tau}$$

- Doesn't fit to a line
- BUT

$$\ln N(t) = \ln(N_0 e^{-t/\tau}) = \ln N_0 - t / \tau$$

$$y = A + B \cdot x \text{ where } A = \ln N_0$$
$$\text{and } B = -1 / \tau$$



Admin

- Last lecture!
- Last homework due next Wednesday, 10/9
- Midterm through D2L on 10/14-10/16
 - available for 48 hours
 - 10% of grade
 - similar material to homeworks
 - I'll send out an email with more details